## Exercise

## Computational Optoelectronics and Photonics

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## PROBLEM SHEET II Please prepare by next exercise.

## 3. Simple Pendulum

The equation of motion for a pendulum is given by

$$\ddot{\phi} = -\frac{g}{l}\sin(\phi). \tag{1}$$

(a) Rewrite Eq. (1) as a system of two first order ordinary differential equations and write a program to solve these coupled equations with the help of the *leap-frog* algorithm.



- (b) Plot the solution  $\phi(t)$  for several periods and different initial conditions with GNUPLOT or/and MATLAB. Choose  $\omega(t=0)=0$  (pendulum at rest at the beginning) and different initial angles  $\phi(t=0)$ .
- (c) Change your code in such a way as to determine the length of *one period*. Then, find out numerically up to which starting angle the small angle approximation ( $\sin \phi \approx \phi$ ) holds. Let's say the deviation from the exact solution should be less the 1%. What would you expect from the formula given in the lecture

$$T \approx 2\pi \sqrt{\frac{l}{g}} \left( 1 + \frac{1}{16} \phi_{\text{max}}^2 \right)$$
 ? (2)